Correction Note
to the paper

Feedback control framework for car-like robots
using the unicycle controllers

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We apologize the readers for the mistake made in equation (53) on page 531, which was found by us in paper [1] after its publication in the Robotica Journal. Namely, values of function $s$ defined in equation (53) are always greater or equal to unity: $s(t) \geq 1$ for all $t \geq 0$. On the other hand, the inverse $1/s(t)$, which was used in the left-hand side of (53), belongs to the set $(0, 1]$ (function $s$ was by mistake assigned to this set in definition (53)).

References


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